

A Strong Separation for Adversarially Robust ℓ_0 Estimation for Linear Sketches

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Adversarially Robust Streaming

- Input:** Elements of an underlying data set S , which arrives sequentially and *adversarially*
- Output:** Evaluation (or approximation) of a given function
- Goal:** Use space *sublinear* in the size m of the input S

- Adversarially Robust:** “Future queries may depend on previous queries”
- Motivation:** Database queries, adversarial ML



1 4 2

3



1 4 2 1

4



Distinct Elements

- Given a set S of m elements from $[n]$, let f_i be the frequency of element i . (How often it appears)
- Let F_0 be the frequency moment of the vector:

$$F_0 = |\{i : f_i \neq 0\}|$$

- Goal:** Given a set S of m elements from $[n]$ and an accuracy parameter ε , output a $(1 + \varepsilon)$ -approximation to F_0
- Motivation:** Traffic monitoring

Linear Sketch

- Algorithm maintains Ax for a matrix A throughout the stream
 - In the streaming model, the entries of A should be *poly(n)* bounded integers
- All insertion-deletion streaming algorithms on a sufficiently long stream might as well be linear sketches [LNW14, AHLW16]

Our Contribution

- There is a constant $\varepsilon = \Omega(1)$ such that any linear sketch that produces $(1 + \varepsilon)$ -approximation to ℓ_0 on an adversarial insertion-deletion stream using $r < n^c$ rows, for a constant $c > 0$, can be broken in $\tilde{O}(r^8)$ queries.

Attack Outline

- Adversary wants to gradually learn the sketching matrix
- Strategy:**
 - Iteratively identify the significant coordinates and set them to zero in all future queries
 - After we have learned all such coordinates, the query algorithm must rely on the other coordinates, for which the sketch Ax only has “small” information

Pre-processing the Sketch Matrix

- The algorithm has access to linear sketch Ax
- Pre-process the matrix A into a larger matrix A' that separates the significant coordinates: add row e_i for each significant i
- WLOG, we can assume the algorithm actually use A' instead of A . Only gives the algorithm “more” information

$$\begin{matrix} \begin{bmatrix} 0 & 1 & 0 & 1 & 0 & 0 & 0 \\ 1 & 999 & 1 & 1 & 0 & 1 & 1 \end{bmatrix} & \longrightarrow & \begin{bmatrix} 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 1 & 1 & 0 & 1 & 1 \\ 0 & 1 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \\ A & & A' \end{matrix}$$

- Iterative process: whenever there is a significant i , zero column i and add a row e_i .
- Resulting matrix A' is a combination of a sparse part S and a dense part D
- The row of S is one-sparse
- The D has no significant columns
- The columns of S and D are disjoint.

$$A' = \begin{bmatrix} S \\ D \end{bmatrix}$$

We Show only $O(rs \log n)$ rows added to A !

- How to quantify significant coordinates?
- i is significant if there exists:
 - $y \in \mathbb{R}^r$ such that $(\text{FRAC}(y^\top A)_i)^2 \geq \frac{1}{s} \sum_i (\text{FRAC}(y^\top A)_i)^2$

Interactive Fingerprinting Code Problem



- Make a number of adaptive queries to learn S .
- Query $q^t \in \{0, 1\}^n$



- A set $S \subset [n]$ with $|S| = \ell$
- Observe q_S^t , output a^t
 - If $q_S^t = 1^\ell$, $a^t = 1$
 - If $q_S^t = 0^\ell$, $a^t = 0$

There exists an interactive fingerprinting code with queries $\tilde{O}(|S|^2)$ [SU15]

Overall Attack

- Pre-process the matrix A into a matrix A' that is a combination of a sparse part S and a dense part D
- Attack sparse part S using fingerprinting code
- Argue dense part D doesn't help

Attacking the Dense Part

- Design a family of distributions \mathcal{D} over $[-R, \dots, -1, 0, 1, \dots, R]$ with $R = \text{poly}(r s \log n)$ such that:
 - For $D_p \in \mathcal{D}$ with $p \in [a, b]$, we have $\Pr_{x \sim D_p}[X = 0] = 1 - p$
 - For any $p, p' \in [a, b]$, the total variation distance between Dx_p and $Dx_{p'}$ is small, i.e., $\frac{1}{\text{poly}(n)}$

$$Ax = \begin{bmatrix} S \\ D \end{bmatrix} x = \begin{bmatrix} Sx_S \\ Dx_D \end{bmatrix}$$

- Dx_D doesn't help to get the value of p , the only help part is Sx_S .