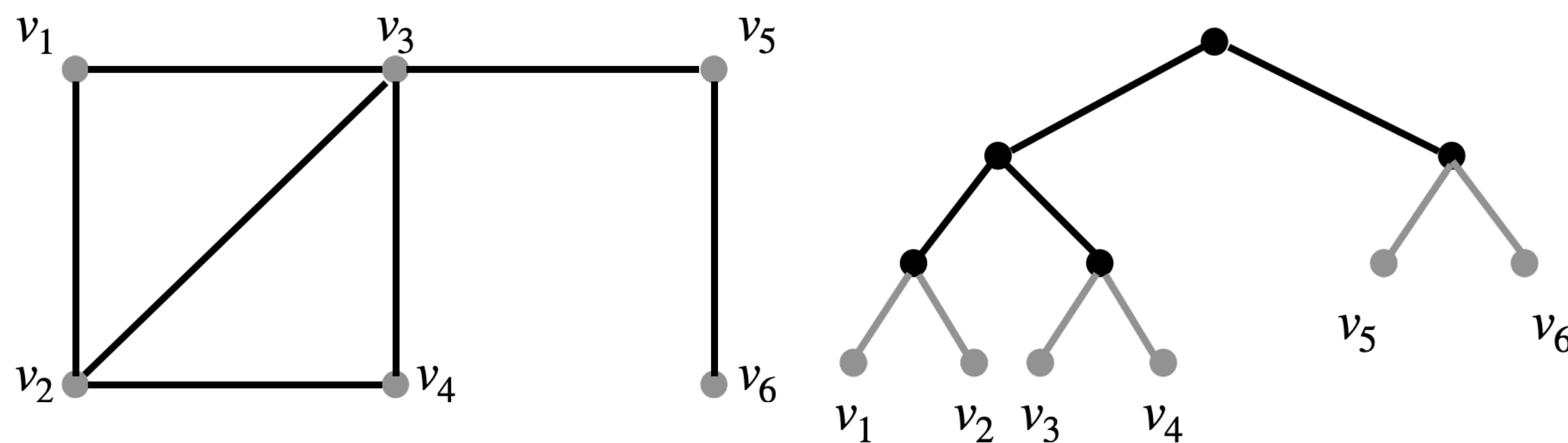


# On the Price of Differential Privacy for Hierarchical Clustering

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## Dasgupta's Cost for HC

➤ **Hierarchical Clustering:** organize data with a hierarchy of clusters



- Vertex: data point
- Edge weight: pair-wise similarity

The hierarchical clustering output can be represented by a tree

➤ **Dasgupta's Cost:** an objective to capture the “quality” of the clustering.

$$\text{cost}_G(T) = \sum_{(i,j) \in E} w_{ij} \cdot |\text{leaves}(T[i \vee j])|$$

$T[i \vee j]$  is the subtree rooted on the lowest common ancestor of  $i, j$

➤ Cost of the above example:

$$\text{cost}_G(T) = 1 \times 6 + 3 \times 4 + 3 \times 2$$

➤ [Das'15, CC'16]: Finding the clustering with minimum cost is **NP-hard**. However, it can be approximated using **sparsest cut** in polynomial time.

## Background

**Approximate Dasgupta's cost with balanced sparsest cut:**

- Sparsity of a graph:  $\phi_G = \min_{S \subseteq V} \frac{w(S, V \setminus S)}{|S|}$ .
- Balanced sparsest cut: the cut induced by  $(S^*, V \setminus S^*)$ . And  $|S^*| = O(n)$ .
- $O(\alpha)$ -approximation of balanced sparsest cut w.r.t. the sparsity gives  $O(\alpha)$ -approximation of the optimal Dasgupta's cost.
- $\alpha = O(\sqrt{\log n})$  for balanced sparsest cut has a poly-time algorithm (A-1).

**Differential privacy models on graphs:**

- Node-DP: Neighboring graphs differ by a node.
- **Edge-DP:** Neighboring graphs differ by an **edge**.
- **Weight-DP:** Neighboring graphs have weights with  $l_1$  difference  $\leq 1$ .

**Prior work on DP Hierarchical Clustering [Imola et al. 23]:**

- Upper Bound:  $\tilde{O}(n^2/\epsilon)$  additive error. But requires **exponential time**.
- Lower Bound:  $\Omega(n^2/\epsilon)$  additive error even when the optimal cost is  $O(n)$ .
- Achieving  $\epsilon$ -DP in the Edge-DP model.

What is the “correct” notion of privacy for hierarchical clustering?

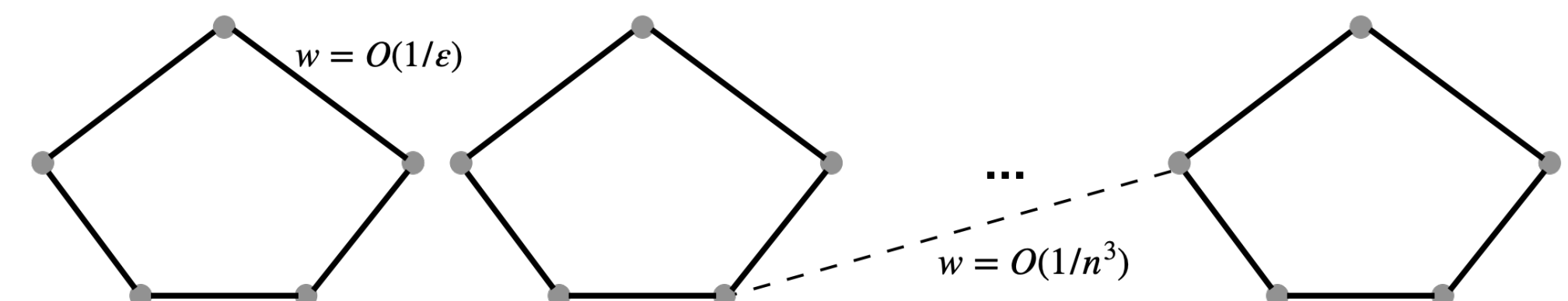
## Main Results

1. The  $\Omega(n^2/\epsilon)$  lower bound even holds for weight-DP model.
2. However, with one assumption that all weights are at least 1, we can achieve  $O(\log^{1.5} n)$ -approximation in poly-time.
3. First algorithm with reasonable implementations for general graphs.

## Lower Bound for Weight-DP

**The additive error of  $\Omega(n^2/\epsilon)$  is necessary in the weight-DP model:**

- Inspired by the lower bound instance for edge-DP
- Main idea: Embed the **disjoint 5-cycle** graphs into a complete graph



**Main argument:**

- To minimize Dasgupta's cost, the algorithm should always partition disconnected components first.
- Any private algorithm will have to cut cycle edges early.

## Private Algorithm

**Unit weight assumption:**

- ☐ We can't afford “**significant changes**” on important edges.
- ☐ Perspective from DP: neighboring graphs differ at an **atomic level**.
- ☒ **Not a trivialization:** input perturbation or output perturbation **✗**  
Add Lap(1/epsilon) to each edge weight, then compute the sparsest cut. Compute all cuts, then add Lap(phi\_G/epsilon) to each and output the sparsest cut.
- ☐ Adding noise may change the sparsity a lot!

**Private algorithm for balanced sparsest cut:**

- Add  $O(\log n/\epsilon)$  to all edge weights. Amplify the gap between sparse and non-sparse cuts
  - Add independent  $\text{Lap}(1/\epsilon)$  to all edge weights (**input perturbation**).
  - Run algorithm A-1 on the perturbed graph and return the cut.
- Recursively call the above algorithm, we get private algorithm for HC.

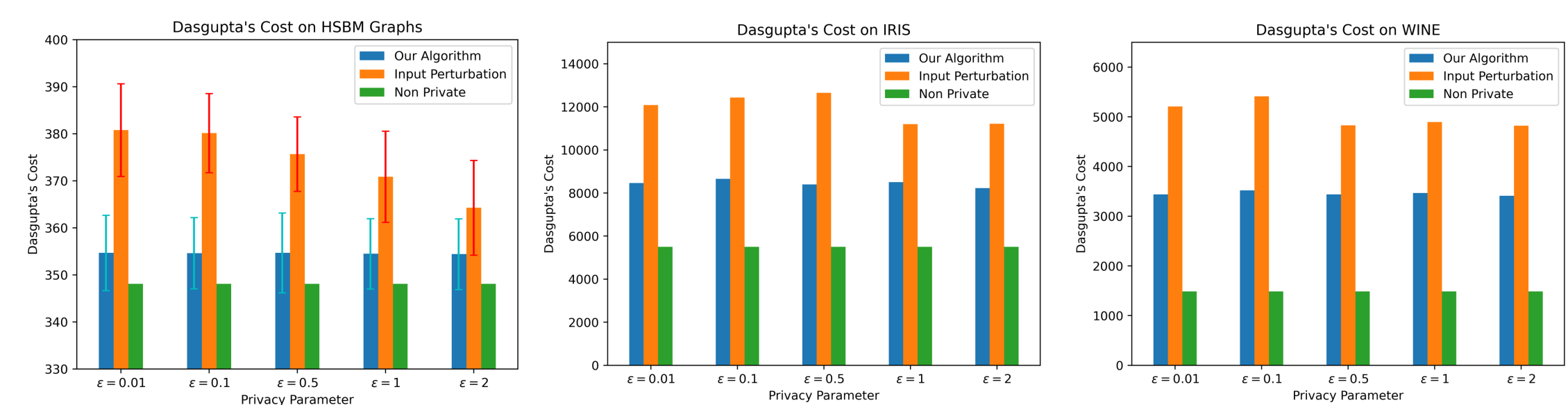
**Analysis:**

- ✓ **Privacy:** Achieved by Input perturbation with Laplace mechanism.
- ✓ **Utility:**  $O(\log^{1.5} n)$  multiplicative error for HC has two sources:
  - a)  $O(\sqrt{\log n})$ -approximation from algorithm A1 for sparsest cut.
  - b)  $O(\log n)$ -approximation due to the Laplace noise.

## Experiments

**Datasets and Baseline:**

- Synthetic: SBM and HSBM graphs
- Real-world: datasets from sk-learn (standard in the literature)
- Baseline: Input perturbation



**Comparing the Dasgupta's Cost:**

- For well-clustered graphs, our algorithm performs close to non-private.
  - For all graphs, our algorithm performs better than input perturbation.
- Our algorithm scales well to large graphs.**

## Open Problem

1. Any approximate-DP algorithm for this model?
2. More applications of the DP sparsest cut algorithm?
3. Long shot: Hierarchical Agglomerative Clustering?

## References

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